

GUIDE TO THE LAYOUT OF ROBOT WORKSTATIONS

Step 1: fix(install) the robot .

Step 2: Put the positioner in the appropriate position (estimated approximate position), please DON'T fix(install) the positioner

Step3: place workpiece on the positioner

Step 4: move the robot welding torch and try to touch the nearest and farthest point of the workpiece.

If the welding torch can well touch the nearest and farthest welding point of the workpiece, then the position of the positioner is good, and the positioner can be fixed.

If not, then Move the position of the positioner until the above conditions are met